OPEN SOURCE ROBOTS: TO MAKE, OR NOT TO MAKE?

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OPEN SOURCE

OPEN SOURCE ROBOTS

SHARING THE TOOLS

TO MAKE, OR NOT TO MAKE?



OPEN SOURCE QUIZZ 1/4

Case 1: my code is in a public repository.

Is it open source?

OPEN SOURCE QUIZZ 2/4

Case 2: my code is on a USB stick I gave to a friend.

Is it open source?

OPEN SOURCE QUIZZ 3/4

Case 3: my code is in a public repository, with the GPLv3 license.

Is it open source?

OPEN SOURCE QUIZZ 4/4

Case 4: my code is in a public repository, with the CC-BY-NC license.

Is it open source?

ANSWERS

My code is ... Is it open source?

- 1. Public: maybe not
- 2. USB stick: maybe
- 3. Public, GPLv3: yes
- 4. Public, CC-BY-NC: no

OPEN SOURCE PROGRAMS

The goal of open source is to foster conditions for collaboration.

The Open Source Definition (1998):

- Free redistribution (1): no royalty, software can be sold, ...
- Source code (2-4): is included, can be modified, ...
- No discrimination (5–10): against persons, fields, joint software, ...

(Says nothing about the capacity of users to run the software.)

OPEN SOURCE ROBOTS

Define "open source" for robots:

- 1. Software: open source license (copyleft or permissive)
- 2. Mechanics: which license?
- 3. **Electronics:** which license?

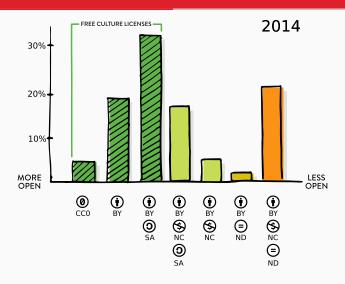
Copyleft? Permissive? Creative Commons?

OSHWA?²

¹Thanks to Olivier Stasse for pointing this out (this is incomplete in what follows!)

²Thanks to Thomas Flayols for pointing this out.

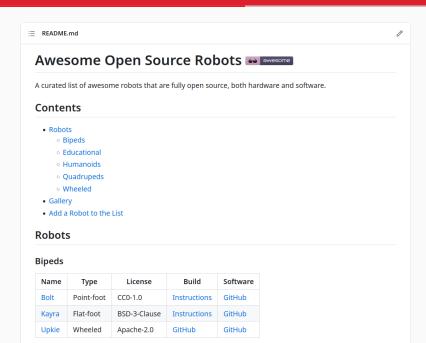
CREATIVE COMMONS LICENSE USE



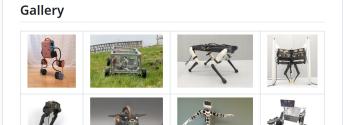
License: Free-cultural-license-cc.svg, Wikimedia Commons (CC-BY-4.0)



AWESOME OPEN SOURCE ROBOTS



AWESOME OPEN SOURCE ROBOTS



Add a Robot to the List

New robots are welcome to the list, as long as they are open source in both hardware and software.

https://github.com/tasts-robots/awesome-open-source-robots

OPEN DYNAMIC ROBOT INITIATIVE

· Software:

Released: ✓

· License: BSD-3-Clause

· Mechanics:

Released: ✓

· License: BSD-3-Clause

· Electronics:

· PCB: ✓

Firmware: ✓

· License: BSD-3-Clause

Build instructions: ✓





https://open-dynamic-robot-initiative.github.io/

UPKIE WHEELED BIPED

· Software:

Released: ✓

· License: Apache-2.0

· Mechanics:

• Released: ✓

· License: Apache-2.0

• Electronics: (from mjbots)

• PCB: ✓

Firmware: ✓

· License: Apache-2.0

Build instructions: ✓



https://github.com/tasts-robots/upkie

NIMBRO-OP2X

· Software:

Released: ✓

· License: BSD-3-Clause

· Mechanics:

· Released: ✓

License: CC-BY-NC-SA-3.0*

* not open source

· Electronics: ?

· Build instructions: ×



NOT OPEN SOURCE (YET)

Works in progress that may become open source (nudge nudge!):

	License	Released	Instructions	At JNRH?
Borinot	not yet	not yet	not yet	Fri 15:30-15:45
Rhea	?	partially	-	-
Sassa	\checkmark	not yet	not yet	Fri 10:30-11:30



SHARING THE TOOLS

What Technology Wants

What Technology Wants is a 2010 nonfiction book by Kevin Kelly focused on technology as an extension of life. Wikipedia



Author: Kevin Kelly

Subjects: Culture, Human, Life, Technology

Publisher: Viking Press



↓ Tools

MJBOTS STACK

· Software:

· Released: ✓

· License: Apache-2.0

· Mechanics:

Released: ✓

· License: Apache-2.0

· Electronics:

• PCB: ✓

• Firmware: <

· License: Apache-2.0

• Support: empirically $\approx 24/7$ on Discord



https://mjbots.com/

MJBOTS PRODUCTS



980



moteus r4.11 controller \$104.00 USD



moteus r4.11 developer ki \$224.00 USD



moteus r4 heat spreado \$29.00 USD



qdd100 beta 3 servi



moteus-n1 \$159.00 USD



gdd100 beta 3 developer xi \$659.00 USD



moteus n1 developer \$279.00 USD



\$29.00 USD

https://mjbots.com/

TO MAKE, OR NOT TO MAKE?

THANK YOU FOR YOUR ATTENTION!

"Seul, on va plus vite. Ensemble, on va plus loin."

